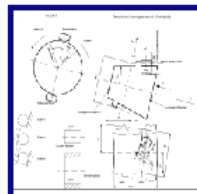
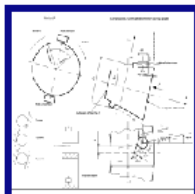
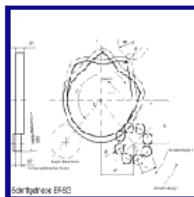


# OPTIMUS MOTUS ® Indexing Cams



NOLTE NC-Kurventechnik   
COMPETENCE IN MOTION DESIGN





## OPTIMUS MOTUS® Indexing Cams

OPTIMUS MOTUS® can be extended by a module for calculating globoidal, cylindrical, parallel indexing cams and cycloidal cam gears:

- calculation, graphics and tables for the cam contours
- automatic cut-off for contour segments outside the cam part
- neutral and machine-specific NC-programs for milling and grinding
- automatic enhancements for the NC-contours of indexing cams for getting into the contour smoothly and for dealing with tolerances
- automatic concatenation of cam tracks
- automatic narrowing of dwell regions
- calculation of the roller durability with respect to the dynamic load changes
- calculation of the overlap when rollers enter or leave the gearing contact
- calculation of the thickness of the flanges
- diagrams and tables for transmission angle and radius of curvature
- diagrams and tables for the Hertz Pressure
- diagrams and tables for driving torque and power
- calculation of the least possible width respectively diameter of the cam part
- calculation of the minimum required time for constant velocity in the law of motion
- calculation of the maximum possible load on the output shaft of the cam
- calculation of the maximum possible speed of the cam shaft with given loads
- output of all the results summarized on one page

**System requirements:** Windows XP / Vista / 7 / 8 / 10

Updated: 13.3.2017



Dialog box for globoidal cams:

OPTIMUS MOTUS (R)

OK Cancel Help x Config Drucken

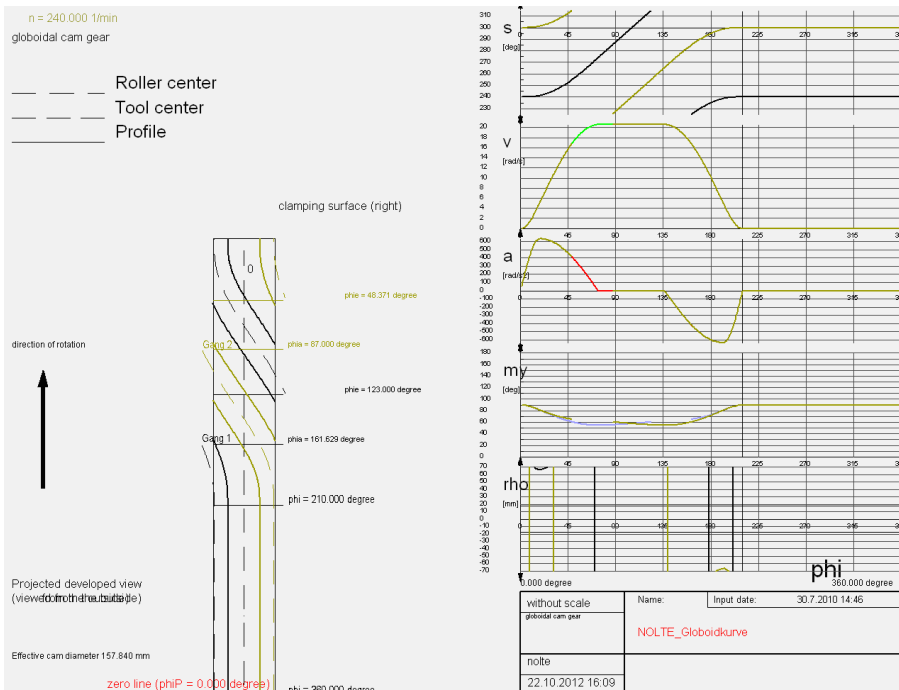
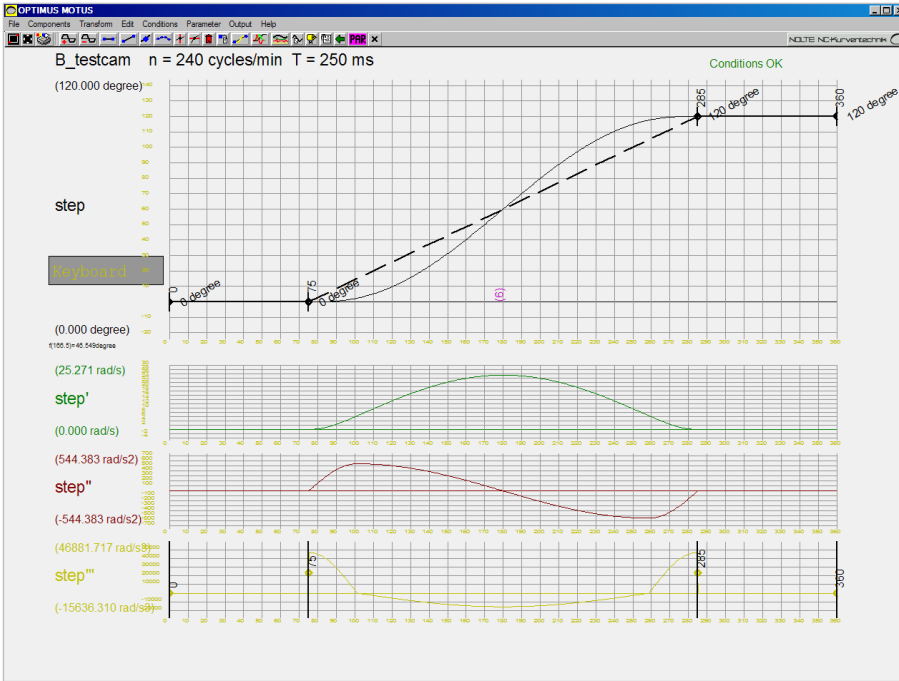
Analysis of a globoidal cam gear

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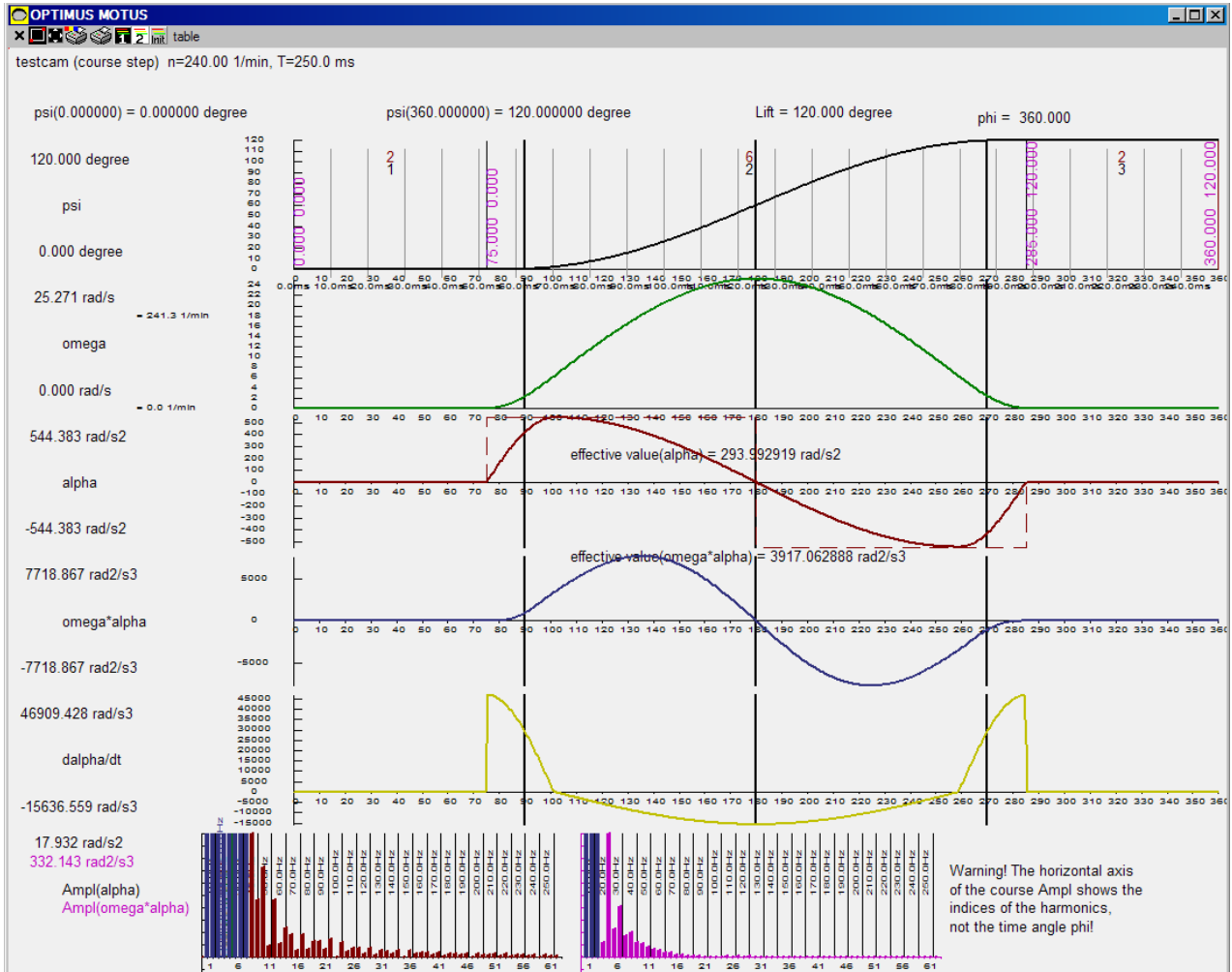
|                                               |         |
|-----------------------------------------------|---------|
| Center distance in mm                         | 140     |
| Pitch radius of the follower in mm            | 65      |
| Number of the rollers                         | 6       |
| Roller diameter in mm                         | 35      |
| Contact length between rollers and cam in mm  | 16      |
| alternative crowning radius in mm             |         |
| Dynamic bearing capacity of the roller in N   | 6000    |
| Peak roller force in N                        | 10000   |
| Start position                                | 2       |
| 1 = roller central, AR                        |         |
| 2 = rollers symmetrical, 2 rollers            |         |
| Cam width in mm (0 = automatic calculation)   | 67      |
| Depth of milling in mm                        | 25      |
| Contact depth of the roller in mm             | 12      |
| Stepping angle in degree                      | *** 120 |
| Cam rotation angle for output motion          | *** 210 |
| Type of motion law (MS, P5, TR, no.)          | *** MS  |
| Share of straight line in %                   | *** 30  |
| Mass moment of inertia on the output in kg*m2 | 0.5     |
| Cycle speed in RPM                            | 150     |

User interface can be switched dynamically between German and English.

Powerful graphical editor for the displacement plan:



Developed view of the cam contours



Motion diagram with path, velocity, acceleration, torque, jerk and fourier analysis



## Summarized results on one page:

Analysis of a globoidal cam gear

```

-----
Center distance in mm                      140
Pitch radius of the follower in mm         65
Number of the rollers                      6
Roller diameter in mm                     35
Contact length between rollers and cam in mm 16
  alternative crowning radius in mm
Dynamic bearing capacity of the roller in N 6000
Peak roller force in N                    10000
Start position                             2
  1 = roller central, AR
  2 = rollers symmetrical, 2 rollers
Cam width in mm (0 = automatic calculation) 67
Depth of milling in mm                    25
Contact depth of the roller in mm          12
Stepping angle in degree                   *** 120
Cam rotation angle for output motion       *** 210
Type of motion law (MS, P5, TR, no.)      *** MS
Share of straight line in %                *** 30
Mass moment of inertia on the output in kg*m2 0.5
Cycle speed in RPM                         150

```

One bearing roller

Speed limited by Life time of the roller

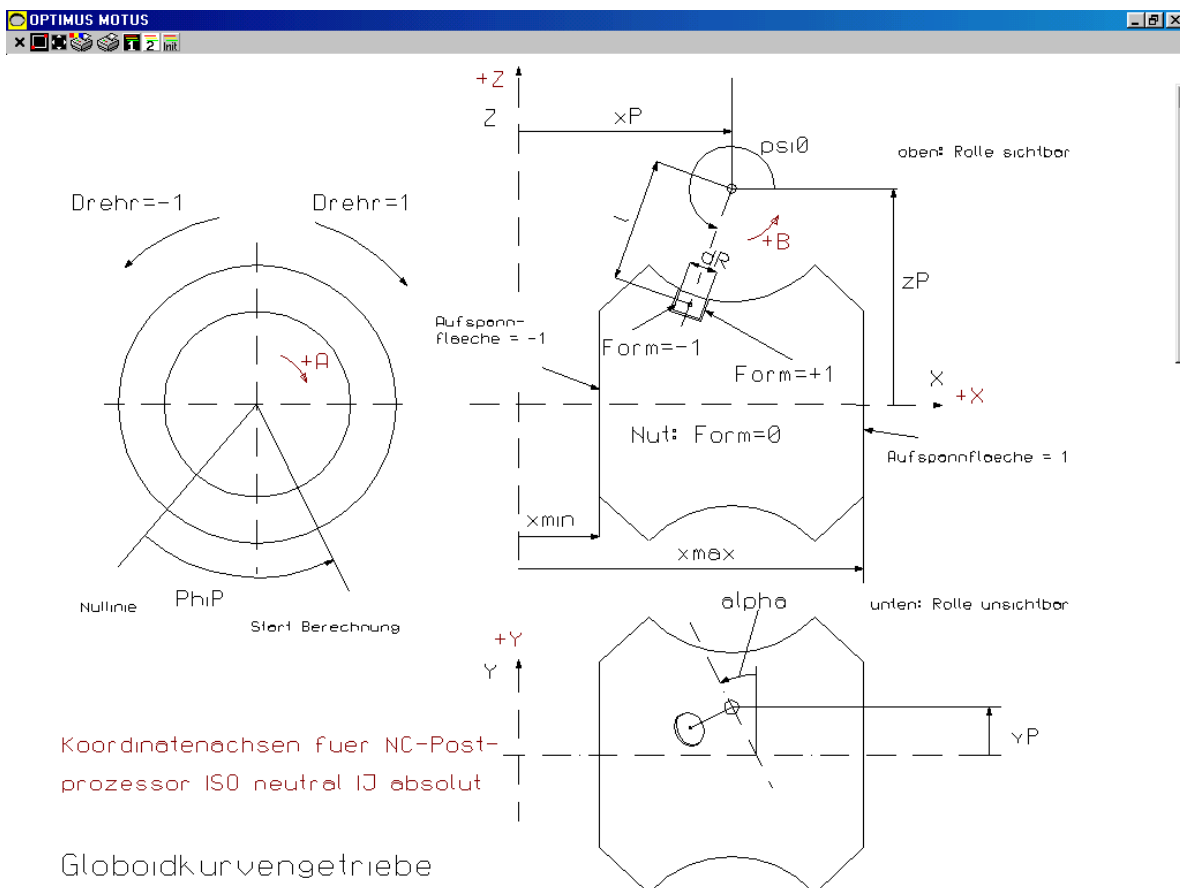
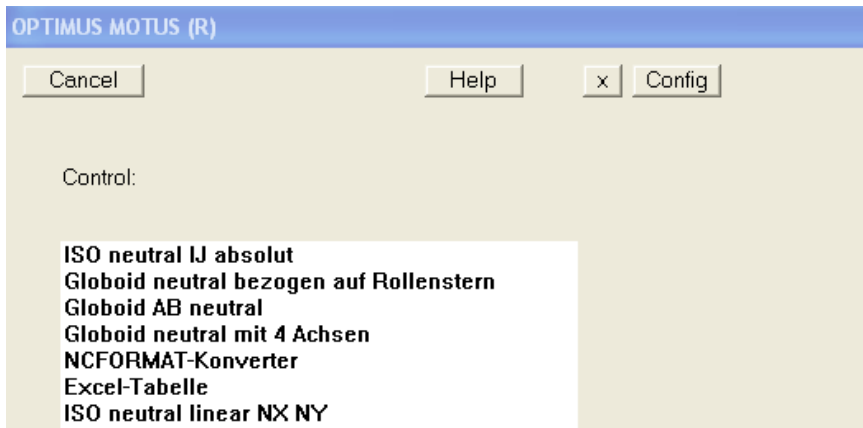
```

Minimum path of overlapping in mm .....: 0.404
Minimum raised ridge width in mm at the top .....: 14.988
Minimum raised ridge width in mm in the middle ..: 20.376
Minimum raised ridge width in mm at the bottom ..: 22.848
Minimum transmission angle in degree .....: 54.687
Min.radius of curvature on profile in mm, top ...: 76.73
Min.radius of curvature on profile in mm, middle : 53.066
Min.radius of curvature on profile in mm, bottom : 33.726
Maximum force on the rollers in N .....: 1932.479
Maximum Hertzian surface stress in N/mm2 .....: 496.154
Maximum driving torque in Nm .....: 56.834
Maximum driving power in kW .....: 1.116
Nominal roller durability in h (single 90 %) ....: 28356.504
Mod. Roller durability in h (total 90%) .....: 9609.089 (single 98.3%)
Cam flank lifetime for 60 HRC in h .....: 4697588.817
Cam flank lifetime for 62 HRC in h .....: 6152654.101
Max. velocity of the output in rad/s .....: 12.863
Max. acceleration of the output in rad/s2 .....: 247.37
-----
Permitted permanent load on the output in Nm ....: 93.567
Max. moment of inertia of the output in kg*m2 ...: 0.731
  corresponding torque on the output in Nm .....: 180.795
Min. width of the cam material in mm .....: 66.9
Min. width by outside dwell-ridges in mm .....: 47.689
Max. permitted cycle speed in RPM .....: 176.919
Required share of straight line in % .....: 0

```

Cam is ok

Standard-NC-postprocessors for globoidal cams, based on different coordinate systems





## Sample of an NC-program for a globoidal cam

ISO neutral IJ absolut:O\_NOLTE\_Globoidkurve (ACHTUNG! NC-Datei mit Begleitprogramm  
NCFORMAT.EXE nachbearbeiten!)

```
N102G1X-101.860Y0.000Z124.030A171.500B231.041
N104G1X-101.304Y0.000Z123.582A171.826B231.293
N106X-100.748Y0.000Z123.139A172.155B231.545
N108X-100.193Y0.000Z122.700A172.487B231.795
N110X-99.640Y0.000Z122.266A172.822B232.044
N112X-99.087Y0.000Z121.837A173.160B232.291
N114X-98.536Y0.000Z121.413A173.500B232.537
N116X-97.986Y0.000Z120.993A173.844B232.782
N118X-97.439Y0.000Z120.579A174.191B233.025
N120X-96.893Y0.000Z120.170A174.541B233.266
N122X-96.350Y0.000Z119.767A174.895B233.505
N124X-95.809Y0.000Z119.368A175.252B233.743
N126X-95.271Y0.000Z118.976A175.613B233.978
N128X-94.737Y0.000Z118.589A175.977B234.212
N130X-94.205Y0.000Z118.207A176.345B234.443
N132X-93.678Y0.000Z117.832A176.716B234.672
N134X-93.154Y0.000Z117.462A177.092B234.899
N136X-92.635Y0.000Z117.099A177.471B235.123
N138X-92.121Y0.000Z116.742A177.855B235.344
N140X-91.612Y0.000Z116.391A178.243B235.563
N142X-91.108Y0.000Z116.047A178.635B235.778
N144X-90.610Y0.000Z115.710A179.031B235.991
N146X-90.119Y0.000Z115.380A179.432B236.200
N148X-89.634Y0.000Z115.057A179.838B236.406
N150X-89.157Y0.000Z114.741A180.248B236.609
N152X-88.688Y0.000Z114.433A180.663B236.807
N154X-88.227Y0.000Z114.132A181.083B237.002
N156X-87.775Y0.000Z113.840A181.508B237.192
N158X-87.332Y0.000Z113.556A181.938B237.378
N160X-86.900Y0.000Z113.280A182.373B237.560
N162X-86.478Y0.000Z113.013A182.813B237.736
N164X-86.068Y0.000Z112.755A183.258B237.908
N166X-85.670Y0.000Z112.506A183.708B238.074
N168X-85.285Y0.000Z112.267A184.164B238.234
N170X-84.914Y0.000Z112.037A184.625B238.388
N172X-84.557Y0.000Z111.818A185.091B238.537
N174X-84.214Y0.000Z111.609A185.562B238.678
N176X-83.888Y0.000Z111.411A186.038B238.813
N178X-83.578Y0.000Z111.224A186.520B238.941
N180X-83.286Y0.000Z111.049A187.006B239.062
N182X-83.011Y0.000Z110.885A187.497B239.175
N184X-82.755Y0.000Z110.732A187.993B239.281
N186X-82.518Y0.000Z110.591A188.492B239.378
N188X-82.300Y0.000Z110.462A188.996B239.468
N190X-82.100Y0.000Z110.345A189.503B239.550
N192X-81.920Y0.000Z110.239A190.014B239.623
N194X-81.759Y0.000Z110.145A190.528B239.690
N196X-81.616Y0.000Z110.061A191.044B239.748
N198X-81.491Y0.000Z109.989A191.562B239.799
N200X-81.384Y0.000Z109.926A192.083B239.843
N202X-81.292Y0.000Z109.873A192.605B239.881
```

...





Dialog box for a planar parallel cam gear:

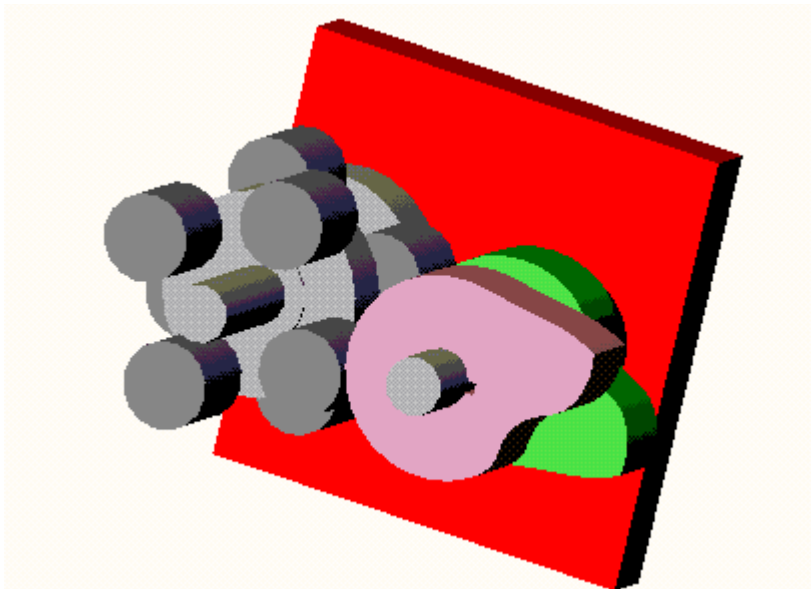
**OPTIMUS MOTUS (R)**

OK Cancel Help x Config Drucken

---

Analysis of a parallel cam gear

|                                               |      |
|-----------------------------------------------|------|
| Center distance in mm                         | 80   |
| Pitch radius of the follower in mm            | 40   |
| Number of the rollers                         | 6    |
| Roller diameter in mm                         | 22   |
| Contact length between rollers and cam in mm  |      |
| alternative crowning radius in mm             | 500  |
| Dynamic bearing capacity of the roller in N   | 5000 |
| Peak roller force in N                        | 6000 |
| Diameter of the cam in mm                     | 110  |
| Thickness of the cam in mm                    | 15   |
| Stepping angle in degree                      | 120  |
| Cam rotation angle for output motion          | 300  |
| Type of motion law (MS, P5, TR, no.)          | MS   |
| Share of straight line in %                   | 30   |
| Mass moment of inertia (output shaft), kg*m2: | 1    |
| Cycle speed in RPM                            | 100  |



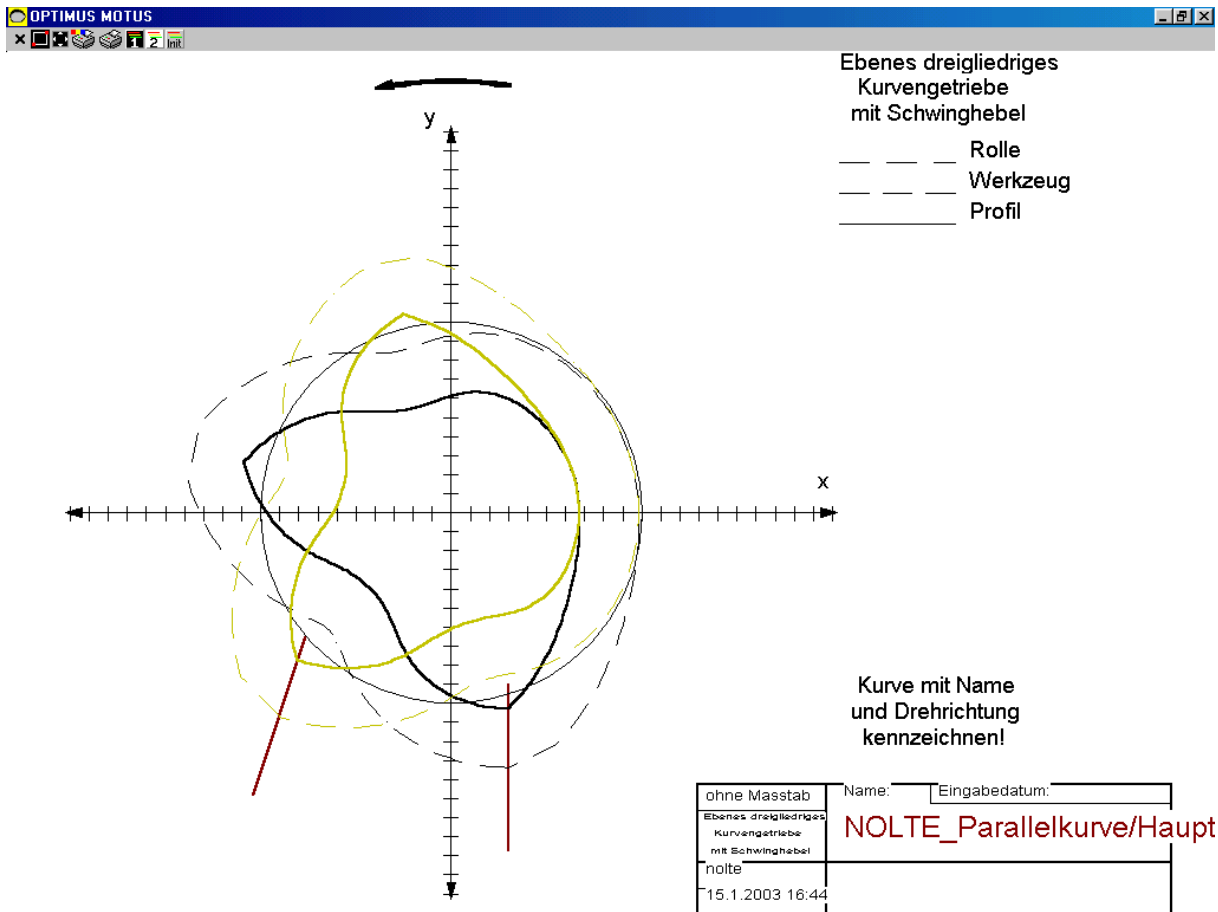


Image of the parallel cams



## Summarized results on one page:

Analysis of a parallel cam gear

```

-----
Center distance in mm                               80
Pitch radius of the follower in mm                 40
Number of the rollers                               6
Roller diameter in mm                              22
Contact length between rollers and cam in mm
  alternative crowning radius in mm                 500
Dynamic bearing capacity of the roller in N        5000
Peak roller force in N                              6000
Diameter of the cam in mm                          110
Thickness of the cam in mm                          15
Stepping angle in degree                           *** 120
Cam rotation angle for output motion                *** 300
Type of motion law (MS, P5, TR, no.)               *** MS
Share of straight line in %                         *** 30
Mass moment of inertia (output shaft), kg*m2:      1
Cycle speed in RPM                                  100
  
```

FOLLOWER IS NOT GUIDED FOR THE WHOLE TIME!  
 --> Overlapping path cannot be calculated  
 TRANSMISSION ANGLE TOO SMALL!

Speed limited by Hertzian surface stress

```

Minimum path of overlapping in mm .....: not available
Minimum transmission angle in degree .....: 1.158
Min. radius of curvature on the profile in mm ...: 21.782
Maximum force on the rollers in N .....: 1537.606
Maximum Hertzian surface stress in N/mm2 .....: 1301.551
Maximum driving torque in Nm .....: 17.328
Maximum driving power in kW .....: 0.227
Nominal roller durability in h (single 90 %) ....: 73468.003
Mod. Roller durability in h (total 90%) .....: 37182.415 (single 96.5%)
Cam flank lifetime for 60 HRC in h .....: 22067.341
Cam flank lifetime for 62 HRC in h .....: 28387.36
Max. velocity of the output in rad/s .....: 6.003
Max. acceleration of the output in rad/s2 .....: 53.874
-----
Permitted permanent load on the output in Nm ....: 36.295
Max. moment of inertia of the output in kg*m2 ...: 1.328
  corresponding torque on the output in Nm .....: 71.555
Min. diameter of the cam in mm .....: not available
Max. permitted cycle speed in RPM .....: 115.247
Max. permitted radius of the follower in mm .: 50.971
Required share of straight line in % .....: 0
  
```

Please check the cam design!



Dialog box for cylindrical indexing cams:

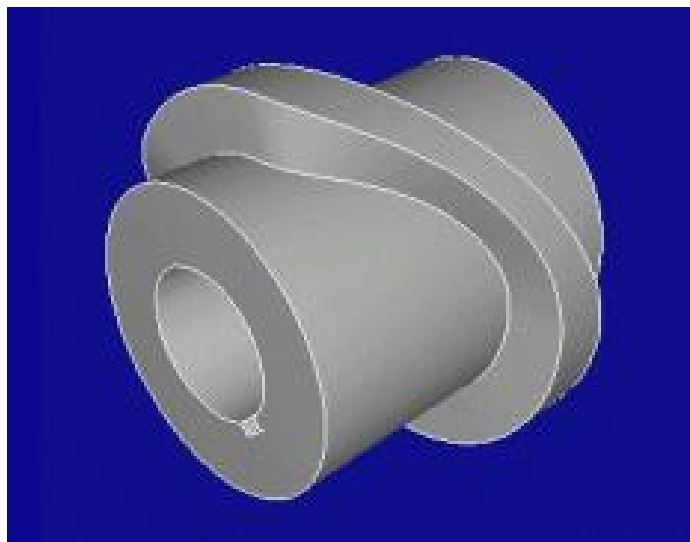
OPTIMUS MOTUS (R)

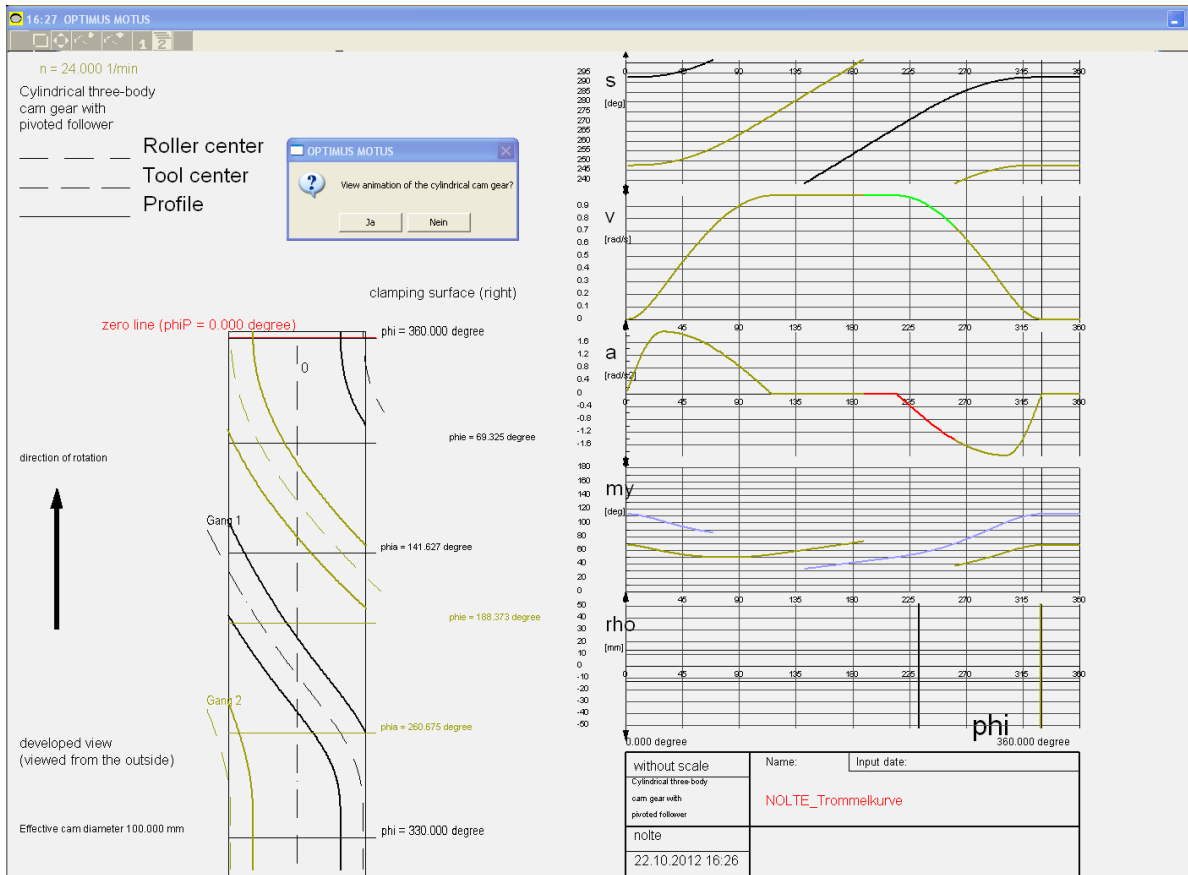
OK
Cancel
Help
x
Config
Drucken

Analysis of a cylindrical cam gear

---

|                                               |      |  |
|-----------------------------------------------|------|--|
| Center distance in mm                         | 100  |  |
| Pitch radius of the follower in mm            | 100  |  |
| Number of the rollers                         | 8    |  |
| Roller diameter in mm                         | 26   |  |
| Contact length between rollers and cam in mm  | 10   |  |
| alternative crowning radius in mm             |      |  |
| Dynamic bearing capacity of the roller in N   | 6000 |  |
| Peak roller force in N                        | 7000 |  |
| Start position                                | 2    |  |
| 1 = roller central, AR                        |      |  |
| 2 = rollers symmetrical, 2 rollers            |      |  |
| Pitch diameter of the cam cylinder in mm      | 100  |  |
| Cam width in mm (0 = automatic calculation)   | 0    |  |
| Depth of milling in mm                        | 20   |  |
| Contact depth of the roller in mm             | 10   |  |
| Stepping angle in degree                      | 90   |  |
| Cam rotation angle for output motion          | 330  |  |
| Type of motion law (MS, P5, TR, no.)          | MS   |  |
| Share of straight line in %                   | 30   |  |
| Mass moment of inertia on the output in kg*m2 | 0.11 |  |
| Cycle speed in RPM                            | 24   |  |





Developed view for cylindrical indexing cams plus animation



## Summarized results on one page:

Analysis of a cylindrical cam gear

```

-----
Center distance in mm                               100
Pitch radius of the follower in mm                 100
Number of the rollers                              8
Roller diameter in mm                             26
Contact length between rollers and cam in mm      10
  alternative crowning radius in mm
Dynamic bearing capacity of the roller in N       6000
Peak roller force in N                             7000
Start position                                     2
  1 = roller centrical, AR
  2 = rollers symmetrical, 2 rollers
Pitch diameter of the cam cylinder in mm          100
Cam width in mm (0 = automatic calculation)       78.9
Depth of milling in mm                            20
Contact depth of the roller in mm                 10
Stepping angle in degree                          *** 90
Cam rotation angle for output motion              *** 330
Type of motion law (MS, P5, TR, no.)              *** MS
Share of straight line in %                       *** 30
Mass moment of inertia on the output in kg*m2     0.11
Cycle speed in RPM                                24

```

One bearing roller

TRANSMISSION ANGLE TOO SMALL!

Speed limited by Life time of the roller

```

Minimum path of overlapping in mm .....:          0.38
Minimum raised ridge width in mm at the top ..:    28.853
Minimum raised ridge width in mm in the middle ..: 23.947
Minimum raised ridge width in mm at the bottom ..: 20.743
Minimum transmission angle in degree .....:        35.57
Min.radius of curvature on profile in mm, top ...: 78.461
Min.radius of curvature on profile in mm, middle : 59.483
Min.radius of curvature on profile in mm, bottom : 35.772
Maximum force on the rollers in N .....:          2.736
Maximum Hertzian surface stress in N/mm2 .....:    27.19
Maximum driving torque in Nm .....:               0.046
Maximum driving power in kW .....:                0
Nominal roller durability in h (single 90 %) ....: 6.52e+014
Mod. Roller durability in h (total 90%) .....:    1.87e+014 (single 98.7%)
Cam flank lifetime for 60 HRC in h .....:         1.09e+015
Cam flank lifetime for 62 HRC in h .....:         1.43e+015
Max. velocity of the output in rad/s .....:        0.982
Max. acceleration of the output in rad/s2 .....:    1.924
-----
Permitted permanent load on the output in Nm ....: 257.048
Max. moment of inertia of the output in kg*m2 ...: 206.417
  corresponding torque on the output in Nm .....: 397.073
Min. width of the cam material in mm .....:         78.9
Min. width by outside dwell-ridges in mm .....:    50.537
Max. permitted cycle speed in RPM .....:          635.928
Min. diameter of the cam cylinder .....:          213.547
Required share of straight line in % .....:         100

```

Please check the cam design!



## Available Laws of motion in OPTIMUS MOTUS®:

|    |                                                 |
|----|-------------------------------------------------|
| 1  | Linear dwell                                    |
| 2  | Circular dwell                                  |
| 3  | Cycloidal motion                                |
| 4  | Polynomial 5th order                            |
| 5  | Modified trapezoidal                            |
| 6  | Modified sine                                   |
| 7  | Simple sine                                     |
| 8  | General cycloidal motion                        |
| 9  | Harmonic motion law                             |
| 10 | Polynomial 5th order with straight line         |
| 11 | Polynomial 11th order                           |
| 12 | Squared parabola                                |
| 13 | Modified sine G-G                               |
| 14 | Sine-straight line-combination U-U              |
| 15 | Modified trapezoidal R-U                        |
| 16 | Harmonic combination R-U                        |
| 17 | Harmonic combination G-U                        |
| 18 | Polynomial 5th order B-B                        |
| 19 | Straight line                                   |
| 20 | Modified trapezoidal U-U                        |
| 21 | Spline1                                         |
| 22 | Cubic splines                                   |
| 23 | Acceleration polygon type A                     |
| 24 | Modified harmonic combination type A            |
| 25 | Modified harmonic combination type B            |
| 26 | Trigonometric cos-splines                       |
| 27 | Law M1                                          |
| 28 | Polynomial 8 <sup>th</sup> order                |
| 29 | Acceleration polygon general                    |
| 30 | Low-noise cosine combination                    |
| 31 | Polynomial 3 <sup>rd</sup> order                |
| 32 | Polynomial 4 <sup>th</sup> order                |
| 33 | Polynomial 6 <sup>th</sup> order                |
| 34 | Polynomial 7 <sup>th</sup> order                |
| 35 | Polynomial max. 20th order with coefficients    |
| 36 | Polynomial max. 20th order with conditions      |
| 37 | Table of values                                 |
| 38 | Reflected sine                                  |
| 39 | Fourier series                                  |
| 40 | Constant value 1                                |
| 41 | Modifizied sine with inserted straight line R-R |
| 42 | Synchronous operation                           |
| 43 | Modifizied harmonic combination type C          |
| 44 | Modifizied harmonic combination type D          |
| 45 | List of dwell-to-dwell-transitions              |
| 46 | General Sine Combination                        |
| 47 | Double Harmonic                                 |
| 48 | Energy saving Polynomial 1                      |
| 49 | Energie saving Polynomial 2                     |
| 50 | Polynomial 15 <sup>th</sup> order               |
| 51 | Freudenstein 1-3                                |
| 52 | Gutman F-3                                      |
| 53 | Berzak D                                        |
| 54 | Berzak E                                        |
| 55 | Peisekah 11 <sup>th</sup> degree                |
| 56 | Polynomial Spline                               |
| 57 | Polynomial 7 <sup>th</sup> degree A             |
| 58 | Polynomial 13 <sup>th</sup> degree              |
| 59 | HS motion law RR                                |
| 60 | YMS-3                                           |
| 61 | YCMV-3                                          |
| 62 | YHP-5                                           |

Names of Motion Laws may differ regionally!